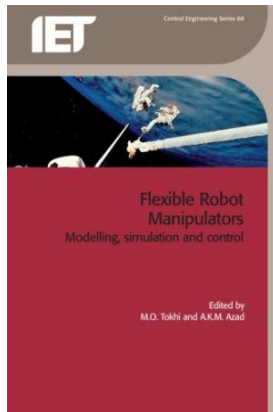


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FLEXIBLE ROBOT MANIPULATORS: MODELLING, SIMULATION AND CONTROL



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